

**A NOTE ON DIVERGENCE-FREE POLYNOMIAL
DERIVATIONS IN POSITIVE CHARACTERISTIC**

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ABSTRACT. In this paper we discuss an explicit form of divergence-free polynomial derivations in positive characteristic. It involves Jacobian derivations.

1. INTRODUCTION

Throughout this paper by a ring we mean a commutative ring with unity.

Let K be a ring. Recall that if d is a K -derivation of the polynomial algebra $K[x_1, \dots, x_n]$ of the form $d = g_1 \frac{\partial}{\partial x_1} + \dots + g_n \frac{\partial}{\partial x_n}$, where $g_1, \dots, g_n \in K[x_1, \dots, x_n]$, then a polynomial

$$d^* = \frac{\partial g_1}{\partial x_1} + \dots + \frac{\partial g_n}{\partial x_n}$$

is called the divergence of d . The derivation d is called divergence-free if $d^* = 0$. See [2] and [3] for information on the properties of the divergence.

Given a polynomial $f \in K[x_1, \dots, x_n]$, we denote by d_{ij}^f a Jacobian derivation of the form

$$d_{ij}^f(g) = \begin{vmatrix} \frac{\partial f}{\partial x_i} & \frac{\partial f}{\partial x_j} \\ \frac{\partial g}{\partial x_i} & \frac{\partial g}{\partial x_j} \end{vmatrix}$$

for $g \in K[x_1, \dots, x_n]$. Of course, $(d_{ij}^f)^* = 0$.

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In the case of positive characteristic, a divergence-free derivation in two variables is closely related to a single Jacobian derivation, see [1], Theorem 4.5. In the general case of n variables a divergence-free derivation is related to a sum of Jacobian ones (Theorem 3.1 below). This fact is well known (compare [4]). The aim of this paper is to give an elementary proof.

Note that the sum in Theorem 3.1 (ii) is different than the one in Theorem 8.3 of Nowicki's article [2]. There arises a natural question if, under the assumptions of Theorem 3.1, the derivation d can be presented in the form $d = \sum_{i=1}^{n-1} d_{i,i+1}^{f_i} + \delta'$, where $f_1, \dots, f_{n-1} \in K[x_1, \dots, x_n]$, and δ' is a K -derivation satisfying

$$\frac{\partial}{\partial x_1}(\delta'(x_1)) = \dots = \frac{\partial}{\partial x_n}(\delta'(x_n)) = 0.$$

2. PRELIMINARIES

Let K be a ring. Let r be a positive integer and $i \in \{1, \dots, n\}$. For every polynomial $g \in K[x_1, \dots, x_n]$ we denote by $g_{i,0}, g_{i,1}, \dots, g_{i,r-1}$ the uniquely determined polynomials belonging to $K[x_1, \dots, x_{i-1}, x_i^r, x_{i+1}, \dots, x_n]$ satisfying the condition

$$g = g_{i,0} + g_{i,1}x_i + \dots + g_{i,r-1}x_i^{r-1}.$$

The following easy observations will be used in the rest of the paper.

Lemma 2.1. *Every polynomial $g \in K[x_1, \dots, x_n]$ can be uniquely presented in the form*

$$g = u + wx_i^{r-1},$$

where $u \in K[x_1, \dots, x_n]$, $u_{i,r-1} = 0$ and $w \in K[x_1, \dots, x_{i-1}, x_i^r, x_{i+1}, \dots, x_n]$. In particular, if $g = 0$, then $u = 0$ and $w = 0$.

Lemma 2.2. *If $g \in K[x_1, \dots, x_{i-1}, x_i^r, x_{i+1}, \dots, x_n]$ and $j \in \{1, \dots, n\}$, $j \neq i$, then*

$$\frac{\partial g}{\partial x_j} \in K[x_1, \dots, x_{i-1}, x_i^r, x_{i+1}, \dots, x_n].$$

In Lemmas 2.3 and 2.4 we assume that K is a ring of prime characteristic p .

Lemma 2.3. *Consider a polynomial $g \in K[x_1, \dots, x_n]$. The polynomial g can be presented in the form*

$$g = \frac{\partial v}{\partial x_i}$$

for some $v \in K[x_1, \dots, x_n]$ if and only if $g_{i,p-1} = 0$.

Lemma 2.4. *Consider a polynomial $g \in K[x_1, \dots, x_n]$. The polynomial g belongs to $K[x_1, \dots, x_{i-1}, x_i^p, x_{i+1}, \dots, x_n]$ if and only if*

$$\frac{\partial g}{\partial x_i} = 0.$$

3. POINCARÉ-TYPE LEMMA

Let K be a ring of prime characteristic p . Consider the algebra of polynomials $K[x_1, \dots, x_n]$. For $i = 1, \dots, n$ put $z_i = \prod_{\substack{j=1, \dots, n \\ j \neq i}} x_j$.

Theorem 3.1 (Poincaré-type Lemma). *Let d be a K -derivation of $K[x_1, \dots, x_n]$, where $n \geq 2$. The following conditions are equivalent:*

- (i) $d^* = 0$,
- (ii) $d = \sum_{1 \leq i < j \leq n} d_{ij}^{f_{ij}} + \delta$, where $f_{ij} \in K[x_1, \dots, x_n]$ for $i < j$ and

$$\delta = h_1 z_1^{p-1} \frac{\partial}{\partial x_1} + h_2 z_2^{p-1} \frac{\partial}{\partial x_2} + \dots + h_n z_n^{p-1} \frac{\partial}{\partial x_n}$$

for some $h_1, \dots, h_n \in K[x_1^p, \dots, x_n^p]$.

Note a version of the above theorem for $n = 1$.

Lemma 3.2. *If d is a K -derivation of $K[x]$, then the following conditions are equivalent:*

- (i) $d^* = 0$,
- (ii) $d = h \frac{\partial}{\partial x}$, where $h \in K[x^p]$.

Remark 3.3. It is convenient to express Theorem 3.1 in terms of polynomials $g_1, \dots, g_n \in K[x_1, \dots, x_n]$, where $d = g_1 \frac{\partial}{\partial x_1} + \dots + g_n \frac{\partial}{\partial x_n}$.

The following conditions are equivalent:

- (i) $\frac{\partial g_1}{\partial x_1} + \dots + \frac{\partial g_n}{\partial x_n} = 0$,
- (ii) there exist $f_{ij} \in K[x_1, \dots, x_n]$ for $i < j$, and $h_1, \dots, h_n \in K[x_1^p, \dots, x_n^p]$, such that

$$\begin{aligned} g_1 &= -\frac{\partial f_{12}}{\partial x_2} - \dots - \frac{\partial f_{1n}}{\partial x_n} + h_1 z_1^{p-1}, \\ g_2 &= \frac{\partial f_{12}}{\partial x_1} - \frac{\partial f_{23}}{\partial x_3} - \dots - \frac{\partial f_{2n}}{\partial x_n} + h_2 z_2^{p-1}, \\ &\vdots \\ g_{n-1} &= \frac{\partial f_{1,n-1}}{\partial x_1} + \dots + \frac{\partial f_{n-2,n-1}}{\partial x_{n-2}} - \frac{\partial f_{n-1,n}}{\partial x_n} + h_{n-1} z_{n-1}^{p-1}, \\ g_n &= \frac{\partial f_{1n}}{\partial x_1} + \dots + \frac{\partial f_{n-1,n}}{\partial x_{n-1}} + h_n z_n^{p-1}. \end{aligned}$$

4. PROOF

Proof. Obviously, (ii) implies (i).

(i) \Rightarrow (ii) We proceed by induction.

Let $n \geq 1$. Consider an arbitrary K -derivation of $K[x_1, \dots, x_n, x_{n+1}]$

$$d = g_1 \frac{\partial}{\partial x_1} + \dots + g_n \frac{\partial}{\partial x_n} + g_{n+1} \frac{\partial}{\partial x_{n+1}},$$

where $g_1, \dots, g_{n+1} \in K[x_1, \dots, x_{n+1}]$.

For each $i \in \{2, \dots, n, n+1\}$ we present g_i in the form $g_i = u_i + w_i x_1^{p-1}$, where $u_i \in K[x_1, \dots, x_{n+1}]$, $(u_i)_{1,p-1} = 0$, $w_i \in K[x_1^p, x_2, \dots, x_{n+1}]$ (Lemma 2.1).

Moreover, we have $u_{n+1} = \frac{\partial v_1}{\partial x_1}$ for some $v_1 \in K[x_1, \dots, x_{n+1}]$ (Lemma 2.3), so

$$g_{n+1} = \frac{\partial v_1}{\partial x_1} + w_{n+1} x_1^{p-1}.$$

Now we compute the divergence:

$$\begin{aligned} d^* &= \frac{\partial g_1}{\partial x_1} + \dots + \frac{\partial g_n}{\partial x_n} + \frac{\partial g_{n+1}}{\partial x_{n+1}} \\ &= \frac{\partial g_1}{\partial x_1} + \frac{\partial}{\partial x_2} (u_2 + w_2 x_1^{p-1}) + \dots + \frac{\partial}{\partial x_n} (u_n + w_n x_1^{p-1}) + \\ &\quad \frac{\partial}{\partial x_{n+1}} \left(\frac{\partial v_1}{\partial x_1} + w_{n+1} x_1^{p-1} \right) \\ &= \frac{\partial g_1}{\partial x_1} + \frac{\partial u_2}{\partial x_2} + \dots + \frac{\partial u_n}{\partial x_n} + \frac{\partial^2 v_1}{\partial x_1 \partial x_{n+1}} + \\ &\quad \frac{\partial w_2}{\partial x_2} x_1^{p-1} + \dots + \frac{\partial w_n}{\partial x_n} x_1^{p-1} + \frac{\partial w_{n+1}}{\partial x_{n+1}} x_1^{p-1}. \end{aligned}$$

We obtain:

$$d^* = F + G x_1^{p-1},$$

where

$$F = \frac{\partial}{\partial x_1} \left(g_1 + \frac{\partial v_1}{\partial x_{n+1}} \right) + \frac{\partial u_2}{\partial x_2} + \dots + \frac{\partial u_n}{\partial x_n},$$

$F \in K[x_1, \dots, x_{n+1}]$, $F_{1,p-1} = 0$, and

$$G = \frac{\partial w_2}{\partial x_2} + \dots + \frac{\partial w_{n+1}}{\partial x_{n+1}},$$

$G \in K[x_1^p, x_2, \dots, x_{n+1}]$.

By Lemma 2.1, if $d^* = 0$, then $F = 0$ and $G = 0$.

Now, let $n = 1$ and assume that $d^* = 0$. We have $g_2 = \frac{\partial v_1}{\partial x_1} + w_2 x_1^{p-1}$, where $v_1 \in K[x_1, x_2]$, $w_2 \in K[x_1^p, x_2]$. Moreover, $\frac{\partial}{\partial x_1}(g_1 + \frac{\partial v_1}{\partial x_2}) = F = 0$ and $\frac{\partial w_2}{\partial x_2} = G = 0$. Hence, $g_1 + \frac{\partial v_1}{\partial x_2} \in K[x_1^p, x_2]$ and $w_2 \in K[x_1^p, x_2^p]$. Then $g_1 + \frac{\partial v_1}{\partial x_2} = u_1 + w_1 x_2^{p-1}$ for some $u_1 \in K[x_1^p, x_2]$, $(u_1)_{2,p-1} = 0$, $w_1 \in K[x_1^p, x_2^p]$ (Lemma 2.1), so $u_1 = \frac{\partial v_2}{\partial x_2}$ for some $v_2 \in K[x_1^p, x_2]$ (Lemma 2.3). Finally,

$$g_1 = -\frac{\partial(v_1 - v_2)}{\partial x_2} + w_1 x_2^{p-1}, \quad g_2 = \frac{\partial(v_1 - v_2)}{\partial x_1} + w_2 x_1^{p-1},$$

where $w_1, w_2 \in K[x_1^p, x_2^p]$. We have shown that for $n = 2$ condition (i) implies (ii).

Assume the statement for some $n \geq 2$, assume that $d^* = 0$.

By the inductive assumption for $K_1[x_1, \dots, x_n]$, where $K_1 = K[x_{n+1}]$, since $F = 0$, we have:

$$\begin{aligned} g_1 + \frac{\partial v_1}{\partial x_{n+1}} &= -\frac{\partial f_{12}}{\partial x_2} - \dots - \frac{\partial f_{1n}}{\partial x_n} + h_1 z_1^{p-1}, \\ u_2 &= \frac{\partial f_{12}}{\partial x_1} - \frac{\partial f_{23}}{\partial x_3} - \dots - \frac{\partial f_{2n}}{\partial x_n} + h_2 z_2^{p-1}, \\ &\vdots \\ u_{n-1} &= \frac{\partial f_{1,n-1}}{\partial x_1} + \dots + \frac{\partial f_{n-2,n-1}}{\partial x_{n-2}} - \frac{\partial f_{n-1,n}}{\partial x_n} + h_{n-1} z_{n-1}^{p-1}, \\ u_n &= \frac{\partial f_{1n}}{\partial x_1} + \dots + \frac{\partial f_{n-1,n}}{\partial x_{n-1}} + h_n z_n^{p-1}, \end{aligned}$$

where $f_{ij} \in K_1[x_1, \dots, x_n]$, $h_i \in K_1[x_1^p, \dots, x_n^p]$ and $z_i = \prod_{\substack{j=1, \dots, n \\ j \neq i}} x_j$.

Moreover, by the inductive assumption for $K_2[x_2, \dots, x_{n+1}]$, where $K_2 = K[x_1^p]$, since $G = 0$, we have:

$$\begin{aligned} w_2 &= -\frac{\partial s_{23}}{\partial x_3} - \dots - \frac{\partial s_{2,n+1}}{\partial x_{n+1}} + a_2 y_2^{p-1}, \\ w_3 &= \frac{\partial s_{23}}{\partial x_2} - \frac{\partial s_{34}}{\partial x_4} - \dots - \frac{\partial s_{3,n+1}}{\partial x_{n+1}} + a_3 y_3^{p-1}, \\ &\vdots \\ w_n &= \frac{\partial s_{2,n}}{\partial x_2} + \dots + \frac{\partial s_{n-1,n}}{\partial x_{n-1}} - \frac{\partial s_{n,n+1}}{\partial x_{n+1}} + a_n y_n^{p-1}, \\ w_{n+1} &= \frac{\partial s_{2,n+1}}{\partial x_2} + \dots + \frac{\partial s_{n,n+1}}{\partial x_n} + a_{n+1} y_{n+1}^{p-1}, \end{aligned}$$

where $s_{ij} \in K_2[x_2, \dots, x_{n+1}]$, $a_2, \dots, a_{n+1} \in K_2[x_2^p, \dots, x_{n+1}^p]$ and $y_i = \prod_{\substack{j=2, \dots, n+1 \\ j \neq i}} x_j$ for $i = 2, \dots, n+1$.

Now, we present each h_i , for $i = 1, \dots, n$, in the form $h_i = b_i + c_i x_{n+1}^{p-1}$, where $b_i \in K[x_1^p, \dots, x_n^p, x_{n+1}]$, $(b_i)_{n+1, p-1} = 0$, $c_i \in K[x_1^p, \dots, x_n^p, x_{n+1}^p]$ (Lemma 2.1).

Then $b_i = \frac{\partial q_i}{\partial x_{n+1}}$ for some $q_i \in K[x_1^p, \dots, x_n^p, x_{n+1}]$, so $h_i = \frac{\partial q_i}{\partial x_{n+1}} + c_i x_{n+1}^{p-1}$ and $\frac{\partial q_i}{\partial x_j} = 0$ for $j = 1, \dots, n$. Denote: $t_i = \prod_{\substack{j=1, \dots, n+1 \\ j \neq i}} x_j$ for $i = 1, \dots, n+1$. We obtain

$$\begin{aligned} g_1 &= -\frac{\partial f_{12}}{\partial x_2} - \dots - \frac{\partial f_{1n}}{\partial x_n} - \frac{\partial(v_1 - q_1 x_2^{p-1} \dots x_n^{p-1})}{\partial x_{n+1}} + c_1 t_1^{p-1}, \\ g_2 &= \frac{\partial f_{12}}{\partial x_1} - \frac{\partial(f_{23} + s_{23} x_1^{p-1})}{\partial x_3} - \dots - \frac{\partial(f_{2n} + s_{2n} x_1^{p-1})}{\partial x_n} \\ &\quad - \frac{\partial(s_{2, n+1} x_1^{p-1} - q_2 x_1^{p-1} x_3^{p-1} \dots x_n^{p-1})}{\partial x_{n+1}} + (c_2 + a_2) t_2^{p-1}, \\ &\quad \vdots \\ g_n &= \frac{\partial f_{1n}}{\partial x_1} + \frac{\partial(f_{2n} + s_{2n} x_1^{p-1})}{\partial x_2} + \dots + \frac{\partial(f_{n-1, n} + s_{n-1, n} x_1^{p-1})}{\partial x_{n-1}} \\ &\quad - \frac{\partial(s_{n, n+1} x_1^{p-1} - q_n x_1^{p-1} x_2^{p-1} \dots x_{n-1}^{p-1})}{\partial x_{n+1}} + (c_n + a_n) t_n^{p-1}, \\ g_{n+1} &= \frac{\partial(v_1 - q_1 x_2^{p-1} \dots x_n^{p-1})}{\partial x_1} + \frac{\partial(s_{2, n+1} x_1^{p-1} - q_2 x_1^{p-1} x_3^{p-1} \dots x_n^{p-1})}{\partial x_2} + \dots \\ &\quad + \frac{\partial(s_{n, n+1} x_1^{p-1} - q_n x_1^{p-1} x_2^{p-1} \dots x_{n-1}^{p-1})}{\partial x_n} + a_{n+1} t_{n+1}^{p-1}. \end{aligned}$$

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